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Learning strategies for sensor-based manipulation tasks

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... the operation order **control** and by modifying the **program module** order ... object (see Image 3). Open the **control** panel and ... A **robot** with a head, body, arm(s) and at ...[www.tc.cornell.edu/Services/vis/dx/cs418/lab3.html](#) - 8k - [Cached](#) - [Similar pages](#)

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robot control system solves the earlier timing problem experienced by ...

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